# **SERVICE MANUAL**

Applicable Sp	pecifications
Programmab	le Tailstock
Applicabl	e Model
SL-150, 150MC, 150Y	TL-40, 40MC, 40Y
SL-200, 200MC	CL-15, 20, 25
SL-250, 250MC	ZL-150, 150MC
SL-300, 300MC	ZL-200, 200MC
SL-400, 400MC	ZL-250, 250MC
Applicable	e NC Unit
<b>MSC-500</b>	MSC-501
MSD-501	MSD-501II
<b>MSC-518</b>	MSD-518
MSD-518	MSC-521

Before starting operation, maintenance, or programming, carefully read the manuals supplied by Mori Seiki, the NC unit manufacturer, and equipment manufacturers so that you fully understand the information they contain.

Keep the manuals carefully so that they will not be lost.



- The contents of this manual are subject to change without notice due to improvements to the machine or in order to improve the manual. Consequently, please bear in mind that there may be slight discrepancies between the contents of the manual and the actual machine. Changes to the instruction manual are made in revised editions which are distinguished from each other by updating the instruction manual number.
- Should you discover any discrepancies between the contents of the manual and the actual machine, or if any part of the manual is unclear, please contact Mori Seiki and clarify these points before using the machine. Mori Seiki will not be liable for any damages occurring as a direct or indirect consequence of using the machine without clarifying these points.
- All rights reserved: reproduction of this instruction manual in any form, in whole or in part, is not permitted without the written consent of Mori Seiki.

The product shipped to you (the machine and accessory equipment) has been manufactured in accordance with the laws and standards that prevail in the relevant country or region. Consequently it cannot be exported, sold, or relocated, to a destination in a country with different laws or standards.

The exportation of this product may be subject to an authorization from the government of the exporting country. Check with the government agency for authorization.

## CONTENTS

1.	GENERAL	P-1
2.	PROCEDURE	FOR SETTING AND CHANGING THE DATA $\dots P-2$
3.	CLAMP POSIT	ION DATA IGRAMMABLE TAILSTOCK
	3.1	Resetting the Clamp Position Data $\dots P - 6$
4.	PC PARAMETI WITH PROGR	ERS RELATED AMMABLE TAILSTOCK P – 9

## 1. GENERAL

This manual deals with the procedure for setting and changing the data in the data table, PC parameters, and timers related with the programmable tailstock.



The parameters are set on shipment in accordance with the machine specifications; do not change them without first consulting Mori Seiki. If the parameters are changed without consultation, the machine may operate in an unexpected manner, causing accidents involving serious injuries or damage to the machine.



Do not change the data carelessly. Improper data will cause damage to the machine.



The configuration of the NC operation panel may vary depending on the specifications of the NC. For the purpose of explanation, NC operation panel used on MSC-500 is used.

## 2. PROCEDURE FOR SETTING AND CHANGING THE DATA

To set or change the data for programmable tailstock, follow the steps indicated below.





ALARM MESSAGE

+

POS

 $\overline{\mathbf{S}}$ 

SYSTEM

ABS

PARAM

PMCLAD

PMCDGN PMCPRM

RUN/STOP

1/0

100 PARAMETER WRITE ENABLE

 $\overline{2}$ 

PROG

?

MESSAGE

REL

DGNOS

PMC CONTROL SYSTEM MENU

SELECT ONE OF FOLLOWING SOFT KEYS

:

:

ALM

-

OFS/SET

1~~

GRAPH

ALL

PMC

SYSTEM

DYNAMIC LADDER DISPLAY DIAGNOSIS FUNCTION PARAMETER (T/C/K/D) RUN/STOP SEQUENCE PROGRAM

: I/O SEQUENCE PROGRAM

Ð

CUSTOM

(OPRT)

MONIT RUN

7)	Press the	1 *	key.
8)	Press the	€ INPUT	(INPUT) key.

The data setting is enable when the following message is displayed:

**"100 PARAMETER WRITE ENABLE"** 

- Press the function selection key (SYSTEM).
- 10) Press the [ PMC ] soft-key.

The PMC CONTROL SYSTEM MENU screen is displayed.

11) Press the [ PMCPRM ] soft-key.

The setting screen for the timers, counters, keep relays, or the data table is displayed.







		A	BS	RI	EL	AI	L					
		OFF	SET	SET	ING	wo	RK		(OP	RT)		
ſī	-							80000		_	<b>1</b>	

PARAMETER WRITE	= =	0	(0 : DISABLE 1 : ENABLE)
TV CHECK	=	0	(0:OFF 1:ON)
PUNCH CODE	=	1	(0: EIA 1: ISO)
INPUT UNIT	=	0	(0:MM 1:INCH)
I/O CHANNEL	=	0	(0-3 : CHANNEL NO.)
SEQUENCE NO.	=	0	(0:OFF 1:ON)
TAPE FORMAT	=	0	(0: NO CNV 1: F 15)
SEQUENCE STOP	=		0 (PROGRAM NO.)
SEQUENCE STOP	=		0 (SEQUENCE NO. )
ICONTRASTI	(+ - 1	∩N·	

12) Press the soft-key corresponding to the data to be set.

#### [ TIMER ], [ COUNTR ], [ KEEPRL ], [ DATA ]

The setting screen for the timers, counters, keep relays, or the data table is displayed in response to the pressed soft-key.

- 13) Move the cursor to the data number for which the data should be set or changed.
- 14) Input the data using the data entry keys.
- 15) Press the 😥 (INPUT) key.
- 16) Set or change the data by repeating steps 12) to 15) above.
- After finishing the setting or changing of the data, press the function selection key (OFS/SET).
- Press the [ SETING ] soft-key.
   The SETTING screen is displayed.
- 19) Press the page selection keys in (return) and in (advance) to display the SETTING (HANDY) screen.
- 20) Move the cursor to "PARAMETER WRITE" using the cursor control keys + and +



- 21) Press the 💿 key.
- 22) Press the 😥 (INPUT) key.



Always return the setting for "PARAMETER WRITE" to "0" to disable parameter change after finishing the setting and changing of the parameter data.

23) Press the (RESET) key to clear the alarm state.

### 3. CLAMP POSITION DATA FOR THE PROGRAMMABLE TAILSTOCK

The clamp position of the programmable tailstock body is written to the data table (retained if power is turned off) and is updated automatically as the tailstock is moved.

If the memory area is cleared, it is necessary to set the clamp position data correctly.



The clamp position data must be set correctly. If the setting is incorrect, the tailstock cannot be connected with the saddle correctly.

#### Resetting the Clamp Position Data

The procedure to set the clamp position data, for the tailstock, is indicated below.

#### <Example>



3.1



AXIS DIRECTION







 Move the saddle to the position where the tailstock can be connected with the saddle by moving the Z-axis with rapid traverse, jog feed, or handle feed operation.





AXIS DIRECTION



TSCLP

TSTMOD



TSUCLP

HANDLE

7) Press the [ **TSUCLP** ] switch.

The tailstock is unclamped and the joint pin extends from the tailstock so that it is connected to the saddle.

The indicator in the [TSUCLP] switch is lit.



If the indicator in the [**TSUCLP**] switch is not lit when the [**TSUCLP**] switch is pressed, follow the procedure below.

- (1) Press the [**TSCLP**] switch to clamp the tailstock once.
- (2) Move the Z-axis to the required position and press the [TSUCLP] switch again.
- After making sure that the indicator in the [TSUCLP] switch has been lit, move the tailstock to the required position in the selected operation mode (rapid feed, jog feed, handle feed).

9) Press the [TSCLP] switch.

The tailstock is clamped; it is disconnected from the saddle.

The indicator in the [**TSUCLP**] switch goes off and the indicator in the [**TSCLP**] switch is lit.

When the tailstock is clamped, the connective position data for storing is automatically updated.

10) Press the emergency stop button.

The on-site adjustment mode is cleared.



4.

## PC PARAMETERS RELATED WITH PROGRAMMABLE TAILSTOCK

This section deals with the PC parameters related with the programmable tailstock.



The parameters are set on shipment in accordance with the machine specifications; do not change them without first consulting Mori Seiki. If the parameters are changed without consultation, the machine may operate in an unexpected manner, causing accidents involving serious injuries or damage to the machine.



For the setting of the parameter, refer to page P - 2 (2.)

Address	Description
PCLPOK. P (D125.6)	1: Clamp is enabled after Z-axis movement in the positive direction (manual mode)
	0: Clamp is disabled after Z-axis movement in the positive direction (manual mode)
	Standard setting is "0".
TSRPD. P (K4.3)	1: Rapid override is 25% or lower while programmable tailstock is unclamped.
	0: Rapid override is 50% or lower while programmable tailstock is unclamped.
	Standard setting is "0".
TSJOG. P (K4.1)	1: Manual rapid traverse rate is fixed at with (fine feed) while programmable tailstock is unclamped.
	0: Manual rapid traverse rate is according to the rapid override while tailstock is unclamped while programmable tailstock is unclamped.
	Standard setting is "0".
TSOCOK. P (D149.2)	1: Unclamp is enabled even when the programmable tailstock is not at the tailstock connective position.
	0: Unclamp is disabled only when the programmable tailstock is at the tailstock connective position.
	Standard setting is "0".
	This parameter is the on-site adjustment parameter.

Address	Description
NTSDEC. P (D279.7)	1: Tailstock feed deceleration switch is not used.
(ZL series)	0: Tailstock feed deceleration switch is used.
	Standard setting is "0".
TSCLSIFT. P (D281.6)	1: Clamp with Z-axis 1 shifted after clamp command is executed.
(ZL series)	0: Unclamp without Z-axis 1 shifted after clamp command is executed.
	Standard setting is "0".

**Comment Form** 

. 19 \_

To improve this manual, we invite you to make comments on any insufficient description or errors in this manual. We want to know how you think we can make this manual better. Please restrict your comments to those concerning this manual only.

♦ Name of manual	PROGRAMMABLE TAILSTOCK OPERATION MANUAL
<ul> <li>Number of revisions</li> </ul>	SM-PTSMSC518-A0E (1997.12)

♦ Name	♦ Company
<ul> <li>Department</li> </ul>	◆ Telephone
<ul> <li>Address</li> </ul>	

+ For Mori Seiki's use - Do not write below this line.

♦ Description	♦ Reception No.	<ul> <li>Received by</li> </ul>